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# Equilibrium Problems and Riesz Representation Theorem

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## Abstract

The purpose of this paper is to give an alternative proof of the Riesz representation theorem using the well-known theorem of Ky Fan minimax inequality applied to equilibrium problems.

**Key words:** Equilibrium problem, Convexity, Monotonicity, Coercivity.

## 1 Introduction

Let  $H$  be a Hilbert space, and let  $H'$  denote its dual space, consisting of all continuous linear functionals from  $H$  into the field  $\mathbb{R}$ . It is very well known that for each  $x \in H$ , the function  $x^* : H \rightarrow \mathbb{R}$  defined by

$$x^*(y) = \langle x, y \rangle, \text{ for all } y \in H$$

where  $\langle \cdot, \cdot \rangle$  denote the inner product of  $H$ , is an element to  $H'$ . The Riesz Representation Theorem states that every element of  $H'$  can be written uniquely in this form (see for instance [2]).

On the other hand, Blum and Oettli introduced the *equilibrium problems* in 1993 (see [1]), as a generalization of various problems such as minimization problems, Nash equilibrium, variational inequalities, etc (see for instance [1, 3]).

Formally, an equilibrium problem, associated to  $K \subset H$  and  $f : K \times K \rightarrow \mathbb{R}$ , consists on finding  $x \in K$  such that

$$f(x, y) \geq 0, \text{ for all } y \in K.$$

The solution set of an equilibrium problem is denoted by  $EP(f, K)$ .

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## 2 Preliminaries

Let  $H$  be a Hilbert space with inner product  $\langle \cdot, \cdot \rangle$  and induced norm  $\| \cdot \|$ . Let  $K$  be a convex subset of  $H$ . Recall that a function  $h : K \rightarrow \mathbb{R}$  is said to be:

- *convex* when for all  $u, v \in K$  and all  $t \in ]0, 1[$  the following holds

$$h(tu + (1 - t)v) \leq th(u) + (1 - t)h(v)$$

- *quasiconvex* when for all  $u, v \in K$  and all  $t \in ]0, 1[$  the following holds

$$h(tu + (1 - t)v) \leq \max\{h(u), h(v)\}$$

- *lower semicontinuous* when for each  $x_0 \in K$  and each  $\lambda < f(x_0)$  there exists  $\delta > 0$  such that for all  $x \in K$  the following implication holds

$$\|x - x_0\| < \delta \Rightarrow f(x) > \lambda.$$

Finally, a function  $f$  is called *concave*, *quasiconcave* or *upper semicontinuous* if  $-f$  is convex, quasiconvex or lower semicontinuous, respectively.

Clearly, all convex functions are quasiconvex. Additionally, a function is continuous if, and only if, it is lower and upper semicontinuous.

A function  $f : K \times K \rightarrow \mathbb{R}$ , defined on  $K \subset H$ , is called:

- *monotone* when  $f(u, v) + f(v, u) \leq 0$ , for all  $u, v \in K$ ;
- *coercive* when for all sequence  $(u_n) \subset K$  with  $\|u_n\| \rightarrow +\infty$  there exists  $u \in K$  such that  $f(u_n, u) \leq 0$ , for all  $n$  large enough.

Usually, the function  $f$  is called *bifunction*.

The following result is due to Ky Fan who proved the famous *minimax inequality*.

**Theorem 2.1** ([4], Theorem 1). *Let  $V$  be a real Hausdorff topological vector space and  $K$  a nonempty compact convex subset of  $V$ . If a bifunction  $f : K \times K \rightarrow \mathbb{R}$  satisfies:*

- $f(\cdot, y) : K \rightarrow \mathbb{R}$  is upper semicontinuous for each  $y \in K$ ,
- $f(x, \cdot) : K \rightarrow \mathbb{R}$  is quasiconvex for each  $x \in K$ ,

*then there exists a point  $x \in K$  such that*

$$\inf_{y \in K} f(x, y) \geq \inf_{w \in K} f(w, w).$$

The above theorem plays an important role in equilibrium problems, because Ky Fan's Theorem implies existence of solutions for these problems.

### 3 An alternative proof of Riesz Representation Theorem

For each  $\phi \in H'$ , we define the bifunction  $f : H \times H \rightarrow \mathbb{R}$  as

$$f(u, v) = \phi(u - v) - \langle u, u - v \rangle \text{ for all } u, v \in H \quad (\text{R})$$

We note that  $f$  satisfies the following property:

(i)  $f(u, u) = 0$ , for all  $u \in H$ .

(ii) Since  $\phi$  and  $\langle \cdot, \cdot \rangle$  are both continuous, we have that  $f$  is continuous.

(iii) For all  $u, v \in H$ ,

$$f(u, v) + f(v, u) = \phi(u - v) - \langle u, u - v \rangle + \phi(v - u) - \langle v, v - u \rangle = -\|u - v\|^2 \leq 0$$

thus,  $f$  is monotone.

(iv) Let  $u \in H$  we note that

$$f(u, \cdot) = \phi(u - \cdot) - \langle u, u - \cdot \rangle.$$

therefore, the function  $f(u, \cdot)$  is affine.

(v) For each  $v \in H$ ,

$$f(\cdot, v) = \phi(\cdot - v) - \|\cdot\|^2 + \langle \cdot, v \rangle$$

The linearity of  $\phi$  and  $\langle \cdot, v \rangle$ , and concavity of  $-\|\cdot\|^2$  imply that  $f(\cdot, v)$  is concave.

**Theorem 3.1** (Riesz Representation Theorem). *For each  $\phi \in H'$ , there exists an unique  $u_0 \in H$  such that*

$$\phi(u) = \langle u_0, u \rangle \text{ for all } u \in H.$$

Moreover,  $\|u_0\| = \|\phi\|_{H'}$ .

In order to proof the above proposition we need the following lemmas.

**Lemma 3.2.** *Let  $f$  defined as (R). If  $u_1, u_2 \in EP(f, H)$  then  $u_1 = u_2$ .*

*Proof.* The monotonicity of  $f$  implies  $f(u_1, u_2) = f(u_2, u_1) = 0$ . So,

$$0 = f(u_1, u_2) + f(u_2, u_1) = \|u_1 - u_2\|^2$$

Therefore  $u_1 = u_2$ . □

*Proof of Theorem 3.1.* The uniqueness follows from Lemma 3.2.

For the existence, we consider  $K = \overline{B}(0, \|\phi\|_{H'})$  which is weakly compact and convex. Since the bifunction (R) satisfies the conditions of Theorem 2.1 on  $K$ , there exists  $u_0 \in K$  such that

$$\inf_{v \in K} f(u_0, v) \geq \inf_{w \in K} f(w, w) = 0$$

i.e.  $f(u_0, v) \geq 0$  for all  $v \in K$  and in particular  $f(u_0, 0) = \phi(u_0) - \|u_0\|^2 \geq 0$ . We want to show that  $f(u_0, \cdot)$  is linear. Since  $f(u, \cdot)$  is affine it is enough to show that  $f(u_0, 0) = \phi(u_0) - \|u_0\|^2 = 0$ . Suppose that  $\|u_0\|^2 < \phi(u_0)$ , then

$$0 \leq \|u_0\|^2 < \phi(u_0) = |\phi(u_0)| \leq \|\phi\|_{H'} \|u_0\| \quad \rightarrow \quad \|u_0\| < \|\phi\|_{H'}$$

and so there exists  $t > 1$  such that  $tu_0 \in K$ . Thus,

$$f(u_0, tu_0) = (1-t)\phi(u_0) - (1-t)\|u_0\|^2 = (1-t)[\phi(u_0) - \|u_0\|^2] \geq 0$$

and this implies  $\phi(u_0) - \|u_0\|^2 \leq 0$  which is a contradiction. Therefore, we have  $\phi(u_0) = \|u_0\|^2$  and  $f(u_0, \cdot)$  is linear.

So, for each  $v \notin K$  there exists  $t \in ]0, 1[$  such that  $tv \in K$ . The linearity of  $f(u_0, \cdot)$  implies  $f(u_0, v) = t^{-1} \times f(u_0, tv) \geq 0$ . Thus,  $u_0 \in EP(f, H)$ . Also by linearity of  $f(u_0, \cdot)$  we have  $f(u_0, -v) \geq 0$  which is true if and only if  $f(u_0, v) \leq 0$  and therefore

$$f(u_0, v) = \phi(u_0 - v) - \langle u_0, u_0 - v \rangle = 0, \quad \text{for all } v \in H$$

which is equivalent to  $\phi(w) = \langle u_0, w \rangle$ , for all  $w \in H$ .

Finally, we note that

$$\|\phi\|_{H'} = \sup_{u \in H, \|u\| \leq 1} \phi(u) = \sup_{u \in H, \|u\| \leq 1} \langle u_0, u \rangle \leq \|u_0\| \leq \|\phi\|_{H'}$$

therefore  $\|\phi\|_{H'} = \|u_0\|$ . □

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